Identification	Subject	ME 420 Theory of Machines, 6 ECTS	
	Department	Mechanical Engineering	
	Program	Undergraduate	
	Term	Fall 2023	
	Instructor	Dr. Mehdi Kiyasatfar	
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	Phone:		
	Classroom/hours	Tuesday, 15:20 -16:50 & 17:00 -18:30	
	Office hours	•	
Prerequisites	Dynamics		
Language	English		
Compulsory/Elective	Compulsory		
<b>Required textbooks</b>	Textbook:		
and course materials	Theory of Machines: Sadhu Singh, Pearson Education, 2nd edition, 2007.		
	Suggested Course Materials:		
	1- F.P. Beer, E.R. Johnston Jr., and W.E. Clausen. Vector Mechanics for		
	Engineers - Dynamics, 7th edition, McGraw-Hill Inc.		
	2- H.H. Mabie and C.F. Reinholz. Mechanisms and Dynamics of Machinery, 4th		
	edition, Wiley.		
	3- G.H. Martin. Kinematics and Dynamics of Machines, 2nd edition, McGraw-		
	Hill.		
	4- Theory of Machines, R. S. Khurmi, J. K. Gupta, S. Chand Publications, New		
Course outline	Delhi 2015.		
Course outline	Having a comprehensive understanding of various mechanisms and machines is a		
	tundamental requirement for mechanical engineers to excel in the industry. The		
	providing essential	insights into the operational principles of any machine	
	Kinematic and dynamic analysis play pivotal roles in the design of mechanisms.		
	and machines		
	Kinematics of machines entails the examination of the relative motion of different		
	components within a machine, often representing one of the initial considerations		
	for a machine's designer. Meanwhile, the dynamics of machines deals with the		
	forces exerted on these components and the resulting motions induced by these		
	forces. Conducting a	a dynamic analysis becomes imperative to ensure that rotating	
	and reciprocating pa	arts are appropriately balanced and that all components meet	
	the required strength criteria.		
	Machines are inherently characterized by their need for mobility to fulfill their		
	intended functions. Consequently, this course is indispensable for mechanical		
	engineering students, enabling them to comprehend motion, the transmission of		
	motion, and the fore	ces responsible for instigating and maintaining motion within	
	machines.	as is designed to introduce the proliminary concents of	
	Theory of Machines is designed to introduce the preliminary concepts of		
	mechanisms and to present methods of analysis for the motion and force		
	used in kinematic ar	d dynamic analysis of machinery to give basic knowledge on	
	kinematic and dyna	mic design of machinery and to give basic knowledge on	
	mechanical vibration		
Course objective	• Study the b	asic components of mechanisms, analyze the assembly with	
	respect to the	ne displacement, velocity, and acceleration at any point in a	
	link of a mechanism and design cam mechanisms for specified output		
	motions.		
	• Study the basic concepts of toothed gearing and kinematics of gear trains.		
	Analyzing th	ne effects of friction in machine elements.	
	Analyzing	the force-motion relationship in components subjected to	
	external for	ces and analyzing of standard mechanisms.	
	Analyzing the second seco	he undesirable effects of unbalances resulting from prescribed	

	motions in mechanism and the effect of dynamics of undesirable					
Learning outcomes	<ul> <li>Upon successful completion of this course, the student will be able to:</li> <li>Discuss the basics of mechanism.</li> </ul>					
	<ul> <li>Solve problems on gears and gear trains.</li> </ul>					
	• Examine friction in machine elements.					
	• Calculate static and dynamic forces of mechanisms.					
	• Calculate the balancing	g masses and their location	ons of reciprocating and			
	rotating masses.					
	• Computing the frequency of free vibration, forced vibration and damping coefficient.					
Teaching methods	Lecture x					
	Case analysis and assignments		Х			
Evaluation	Methods	Date/deadlines	Percentage (%)			
	Midterm Exam		25			
	Class Participation	At each lesson	5			
	Assignment	During the semester	20			
	Quiz	During the semester	10			
	Final Exam		40			
	Total		100			
Toney	<ul> <li>Copy of other students' work is highly discouraged. All assignments must be handled by the student himself. This is a university policy and violators will be reprimanded accordingly.</li> <li>Preparation for class The structure of this course demands your individual effort outside the classroom for extra practice of many problems within the textbook. After each session, every student needs to put sufficient time to practice and finish the assignments by the predetermined date.</li> <li>Withdrawal (pass/fail) This course strictly follows grading policy of the School of Science and Engineering. Thus, a student is normally expected to achieve a mark of at least 60% to pass. In case of failure, he/she will be required to repeat the course the following term or year.</li> </ul>					
	• Cheating/plagiarism Cheating or other plagiarism in handling the assignments, Mid-term and Fina Examinations will lead to course failure. In this case, the student will automatically get zero (0), without any considerations.					
	• <b>Professional behavior guidelines</b> The students shall behave in a way to create favorable academic and professional environment during the class hours. Unauthorized discussions and unethical behavior are strictly discouraged.					
	• Attendance Students who attend the whole classes will get 5 marks. for three absence student loses 1 mark.					
	• Quiz There will be quizzes for chare not going to give make- medical report.	necking understanding of c up for a missing quiz due	content during class. We to any reason other than			
	Assignment					

	There will be a homework assignment for exercises and problems.	every chapter composed of			
Tentative Schedule					
Week	Topics	Textbook/Assignments			
1 Fundamental concepts, Definitions; geometrical categorization of mechanisms; mobility; kinematic inversion; Grashof's law.		Chapter 1			
2 Intro. Graphical solution of vector equations.		Chapter 2			
3	Definitions; velocity polygons; apparent linear velocity of a point; apparent angular velocity; instant centers of velocity.	Chapter 3			
4	Linear acceleration; angular acceleration; acceleration difference vector;	Chapter 4			
5	Acceleration polygons; apparent acceleration; instant centers.	Chapter 4			
6	Acceleration polygons; apparent acceleration; instant centers.	Chapter 4			
7	Preliminaries; forces acting on links; graphical analysis and superposition; analytical force balance and matrix solution.	Chapter 5			
8	Review Midterm Exams				
9	Introduction; balancing of machinery; balancing of rotating shafts. analysis of rotor balancing.	Chapter 6			
10	Kinematics of cams, definition and classification; displacement diagrams, cam profile design,	Chapter 7			
11	Dynamics of cams, rigid cam systems.	Chapter 7			
12	Fundamental law of gearing.	Chapter 8			
13	Automotive transmission, Planetary Gears	Chapter 9			
14	Mechanical Vibrations	Chapter 10			
15	Conclusion – Solve problems				
16	Final Exam				

This syllabus is a guide for the course and any modifications to it will be announced in advance.